

MASS 2023 Course:
Gravitation and Cosmology

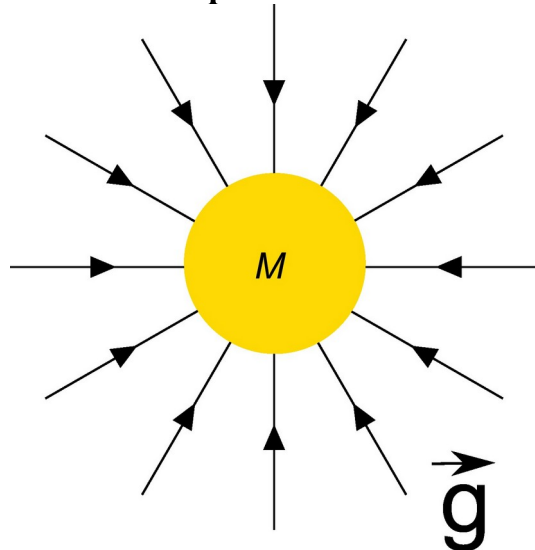
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Lecture 01

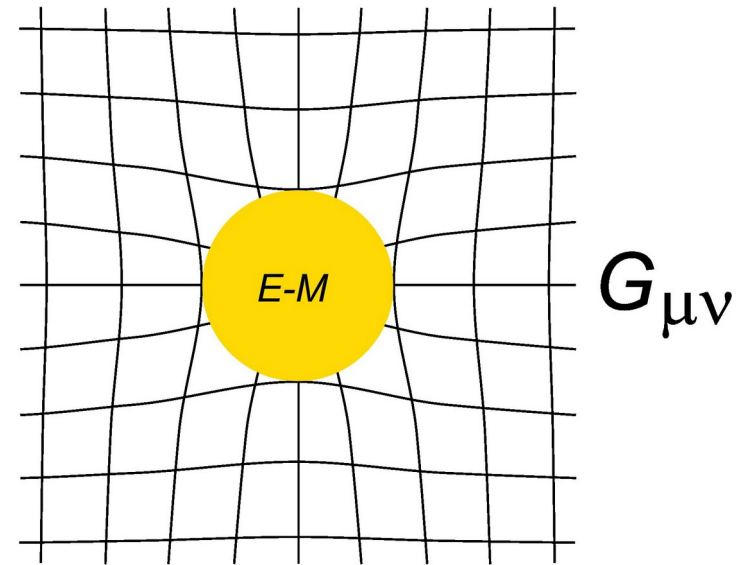
- Gravitational field
- Brief overview of Newton's theory of gravity
- General Relativity (GR) as a geometric theory of gravitation
- Concept of spacetime:
 - events
 - worldlines
- Einstein summation convention
- General coordinate transformations
- Some basic mathematical concepts:
 - Manifolds
- Exercises

Gravitational field

- In physics, a field is a physical quantity, represented by a scalar, vector or tensor, that has a value for each point in space and time
- A function assigning a scalar, vector, or tensor to each point in space and time:
 - scalar fields (temperature, humidity, pressure, ...)
 - vector fields (Newton's gravitational field, electric field, ...)
 - tensor fields (stress and strain in materials, Riemann curvature tensor, ...)
- Gravitational field in Newton's theory of gravity is a vector field that exists in the space around every mass
- In contrast, gravity in General Relativity (GR) is not due to an effective force field, but a result of spacetime curvature



In Newton's theory of gravity, mass is the source of a gravitational field \vec{g}



In GR, mass-energy curves spacetime (Einstein tensor $G_{\mu\nu}$)

Newton's theory of gravity

- The gravitational force between two objects of masses M and m separated by a

vector \vec{r} :
$$\vec{F}(\vec{r}) = -\frac{GMm}{r^2} \hat{r}$$

- The force acts on particle of mass m and gives it an acceleration according to

Newton's second law:
$$\vec{F}(\vec{r}) = m \vec{g}(\vec{r})$$

- Gravitational field is described by gravitational acceleration:
$$\vec{g}(\vec{r}) = -\frac{GM}{r^2} \hat{r}$$

- Equivalently, the gravitational potential Φ is related to the mass density ρ by

Poisson's equation:
$$\nabla^2 \Phi = 4\pi G \rho$$

- The acceleration is then given by the gradient of the potential:
$$\vec{g}(\vec{r}) = -\nabla \Phi(\vec{r})$$

- In the case of point mass M , Newton's gravitational potential is:
$$\Phi(r) = -\frac{GM}{r}$$

- Gradient:
$$\nabla = \left(\frac{\partial}{\partial x_1}, \dots, \frac{\partial}{\partial x_n} \right)$$

- Laplace operator:
$$\Delta f = \nabla^2 f = \nabla \cdot \nabla f = \sum_{i=1}^n \frac{\partial^2 f}{\partial x_i^2}$$
 (divergence $\nabla \cdot$ of gradient ∇)

- Divergence of a vector $\vec{F} = F_x \vec{i} + F_y \vec{j} + F_z \vec{k}$:

$$\text{div } \vec{F} = \nabla \cdot \vec{F} = \frac{\partial F_x}{\partial x} + \frac{\partial F_y}{\partial y} + \frac{\partial F_z}{\partial z}$$

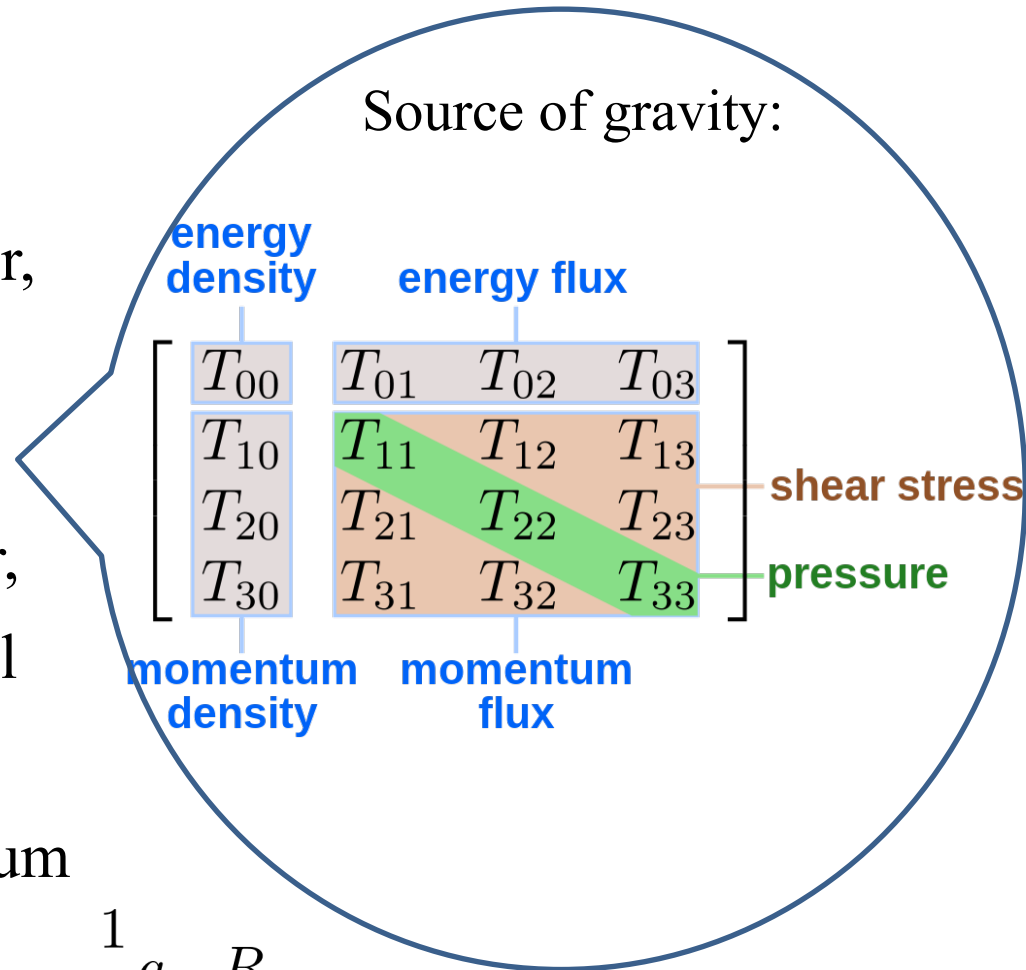
General Relativity (GR)

- GR is the standard theory of gravity, formulated by Albert Einstein in 1915
- It describes gravitation in terms of differential geometry of curved spacetime
- Fundamental interaction of gravitation as a result of spacetime being curved by matter and energy is described by field equations of GR:

$$R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = \frac{8\pi G}{c^4}T_{\mu\nu}$$

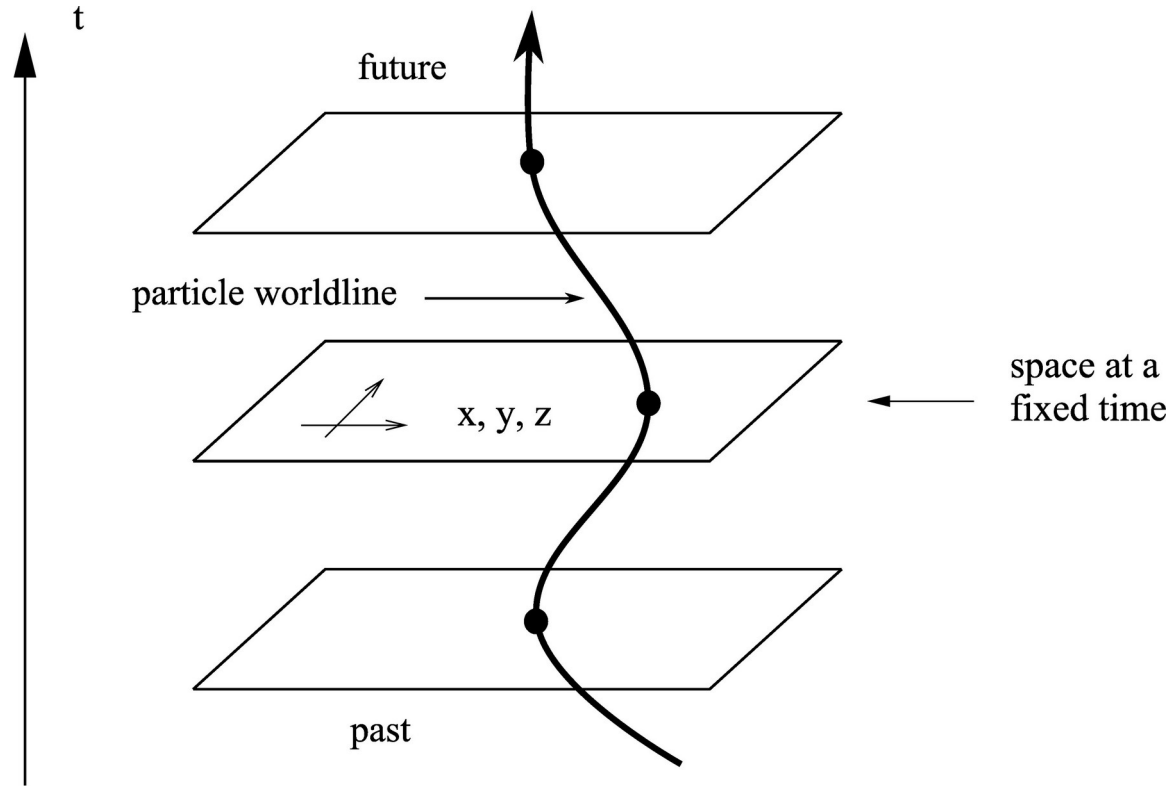
where:

- $R_{\mu\nu}$ - Ricci curvature tensor,
- $g_{\mu\nu}$ - metric tensor,
- $T_{\mu\nu}$ - stress-energy tensor
- R - Ricci curvature scalar,
- G - Newton's gravitational constant,
- c - speed of light in vacuum
- Einstein tensor: $G_{\mu\nu} = R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R$



Concept of spacetime

- **Spacetime** is a 4-dimensional set with elements labeled by 3 dimensions of space and 1 of time
- **Event** is an individual point in spacetime
- **Worldline** is a curve through spacetime (a parametrized 1-dimensional set of events), representing the path of a particle
- In Newtonian mechanics there is:
 - no limit on particle velocity
 - absolute division of spacetime into well-defined slices of space at a fixed moment in time
 - notion of **absolute simultaneity** of two events which occur at the same time
 - **absolute space**: the spatial interval between two simultaneous events is observer independent
 - **absolute time**: time interval between two events has absolute significance and all observers agree on its value
- **Euclidean geometry**: space interval Δl between two simultaneous events is given by Pythagorean theorem:
$$\Delta l^2 = (x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2$$



Some important notation and conventions

- From now on we will use the following notation and convention:
 - Greek indices (α, β, \dots) run from 0 to 3
 - Lower-case latin indices (a, b, \dots) run from 1 to 3
 - **Einstein summation convention:** indices which appear both as superscripts and subscripts are summed over

- Example: $y = \sum_{i=1}^3 c_i x^i = c_1 x^1 + c_2 x^2 + c_3 x^3$ is simplified to: $y = c_i x^i$

- The superscripts are not exponents but are indices of coordinates on spacetime, with 0 denoting the time coordinate: x^μ :

$$\begin{aligned} x^0 &= ct \\ x^1 &= x \\ x^2 &= y \\ x^3 &= z \end{aligned}$$

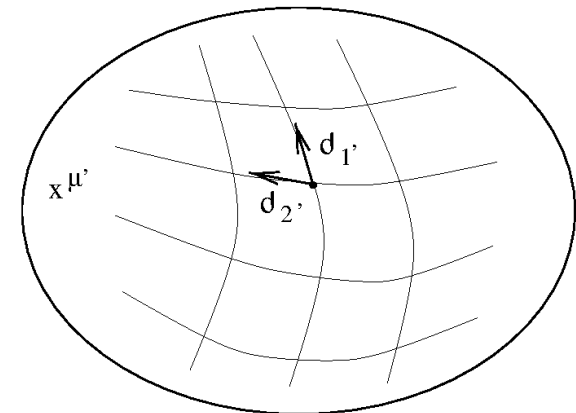
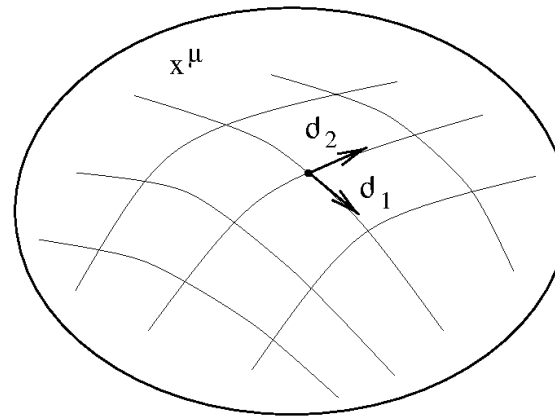
- **General coordinate transformations**

(which must be invertible) and their

inverse transformations:

$$x^\mu \rightarrow x^{\mu'} = x^{\mu'}(x^0, x^1, x^2, x^3)$$

$$x^{\mu'} \rightarrow x^\mu = x^\mu(x^{0'}, x^{1'}, x^{2'}, x^{3'})$$



- A quantity is **invariant** if its value is unchanged under coordinate transformations
- An equation is **covariant** if its form is unchanged under coordinate transformations

GR as a geometric theory of gravity

Physics	Geometry
<ul style="list-style-type: none">• When and the where of a physical phenomenon constitute an event.• The set of all events is a continuous space, named spacetime• Gravitational phenomena are manifestations of the geometry of spacetime• Point-like particles move in spacetime following special world-lines that are “straight”• The laws of physics are the same for all observers	<ul style="list-style-type: none">• An event is a point in a topological space• Spacetime is a differentiable manifold M• The gravitational field is a metric g on M• Straight lines are geodesics• Field equations are generally covariant

Spacetime = Differentiable Manifold

• Newtonian gravity vs. GR:

Gravitational Potentials = Metric

Forces = Connections

Some basic mathematical concepts

- **Mathematical space** is a set of elements called points with some additional features on the set (e.g. an operation, relation, metric or topology)
- **Topology** is set of neighborhoods for each point that satisfy some axioms of closeness
- **Topological space** is a mathematical space with topology (i.e. a mathematical space in which closeness is defined but cannot necessarily be measured by a numeric distance)
- Topological space is the most general type of a mathematical space that allows for the definition of limits, continuity, and connectedness
- Types of topological spaces: Euclidean spaces, metric spaces and manifolds
- n -dimensional **Euclidean space** is set \mathbf{R}^n of all n -tuples of real numbers (x^1, \dots, x^n) , equipped with the scalar (dot or inner) product of two vectors
- **Metric space** is an ordered pair (M, d) where M is a set of points and d is a function called **metric** on M which measures distance between the points.
 - A simple example is Euclidean space \mathbf{R}^3 equipped with Euclidean metric d :

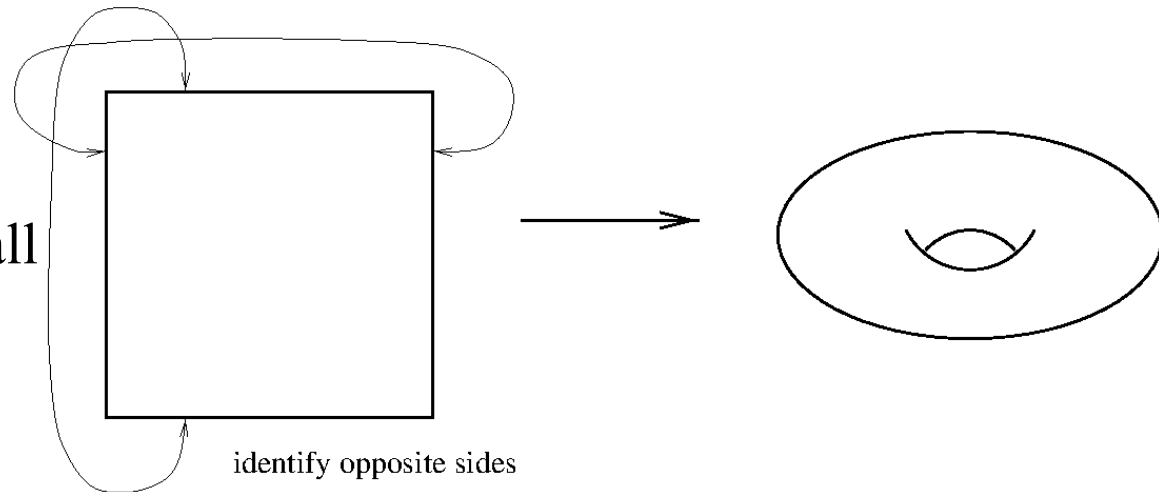
$$d((x_1, y_1, z_1), (x_2, y_2, z_2)) = \sqrt{(x_2 - x_1)^2 + (y_2 - y_1)^2 + (z_2 - z_1)^2}$$

Manifolds

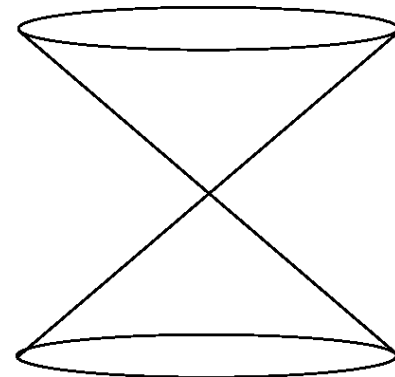
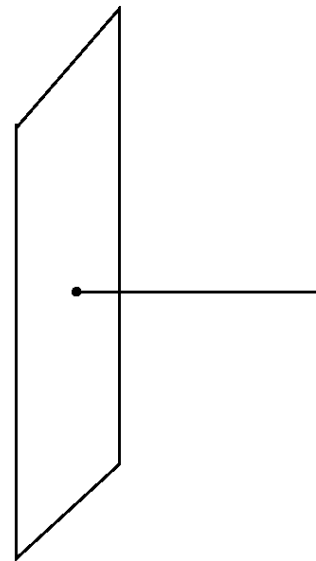
- **Manifold** (or differentiable manifold) is a topological space which may be curved and have a complicated topology, but locally looks like Euclidean space \mathbf{R}^n near each point
- Manifold is constructed by smoothly joining together the Euclidean-like local regions

- Examples of manifolds:

- Euclidean space \mathbf{R}^n
- n -sphere S^n , since it is the locus of all points at some fixed distance from the origin in \mathbf{R}^{n+1}
- The n -torus T^n , since it can be constructed from an n -dimensional cube by identifying its opposite sides



- These are not manifolds because somewhere they do not look locally like \mathbf{R}^n :
 - one-dimensional line running into a two-dimensional plane
 - two cones stuck together at their vertices



Exam question

1. Spacetime as differentiable manifold

Literature

- Textbook: Sean M. Carroll, 1997. Lecture Notes on General Relativity, arXiv, gr-qc/9712019

Exercise 1

- Write down $X_{ij}Y^{ij}$ explicitly as a sum of terms in $n = 2$ and $n = 3$ dimensions, respectively

Exercise 2

- Write down $X_iY^{ij}X_j$ explicitly as a sum of terms in $n = 2$ and $n = 3$ dimensions, respectively, assuming the following symmetry: $Y^{ij} = Y^{ji}$

Solution 1

• In $n = 2$ dimensions: $X_{ij}Y^{ij} = X_{11}Y^{11} + X_{12}Y^{12} + X_{21}Y^{21} + X_{22}Y^{22}$

• In $n = 3$ dimensions:

$$\begin{aligned} X_{ij}Y^{ij} &= X_{11}Y^{11} + X_{12}Y^{12} + X_{13}Y^{13} + X_{21}Y^{21} + X_{22}Y^{22} + \\ &+ X_{23}Y^{23} + X_{31}Y^{31} + X_{32}Y^{32} + X_{33}Y^{33} \end{aligned}$$

Solution 2

- In $n = 2$ dimensions: $X_i Y^{ij} X_j = Y^{11}(X_1)^2 + 2Y^{12}X_1X_2 + Y^{22}(X_2)^2$

- In $n = 3$ dimensions:

$$\begin{aligned} X_i Y^{ij} X_j &= Y^{11}(X_1)^2 + 2Y^{12}X_1X_2 + 2Y^{13}X_1X_3 + Y^{22}(X_2)^2 + \\ &+ 2Y^{23}X_2X_3 + Y^{33}(X_3)^2 \end{aligned}$$