### MASS 2023 Course: Gravitation and Cosmology

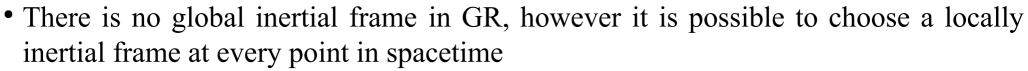
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### Lecture 05

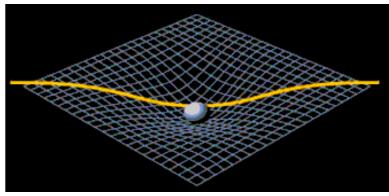
- Locally inertial frame in GR
- Basic principles of GR:
  - 1. The principle of equivalence (strong and weak)
  - 2. The principle of general covariance (the general principle of relativity)
- Affine connection
- Geodesic equation
- Newtonian limit in GR
- Exercises

## **Basics of GR: locally inertial frame**

- GR is formulated by Albert Einstein in 1915 and is currently accepted as the standard theory of gravity
- GR considers curved spacetimes as 4-dimensional Riemannian manifolds and studies accelerated relative motions and gravity
- The presence of matter curves spacetime, and this curvature affects the paths of free particles and light



- Locally inertial frame is a reference frame within a sufficiently small region around the given point, in which the laws of nature take the same form as in inertial reference frame in SR, i.e. in absence of gravitation  $\partial \xi^{\alpha} \partial \xi^{\beta}$
- In a general coordinate system  $x^{\mu}$ , metric  $g_{\mu\nu}$  is defined by:  $g_{\mu\nu} \equiv \eta_{\alpha\beta} \frac{\partial \xi^{\alpha}}{\partial x^{\mu}} \frac{\partial \xi^{\beta}}{\partial x^{\nu}}$ , where  $\xi^{\alpha}$  is a locally inertial coordinate system
- Metric  $g_{\mu\nu}$  can be locally transformed to the Minkowski metric  $\eta_{\mu\nu}$ : for every point *P* in the spacetime, there is a coordinate transformation that makes  $g_{\mu\nu} = \eta_{\mu\nu}$  at *P*
- GR postulates that, in the presence of matter, the global Lorentz covariance of SR becomes a local Lorentz covariance in an infinitesimal region of spacetime at every point, so that SR controls physics only locally
- In GR: gravitation = a field of locally inertial frames

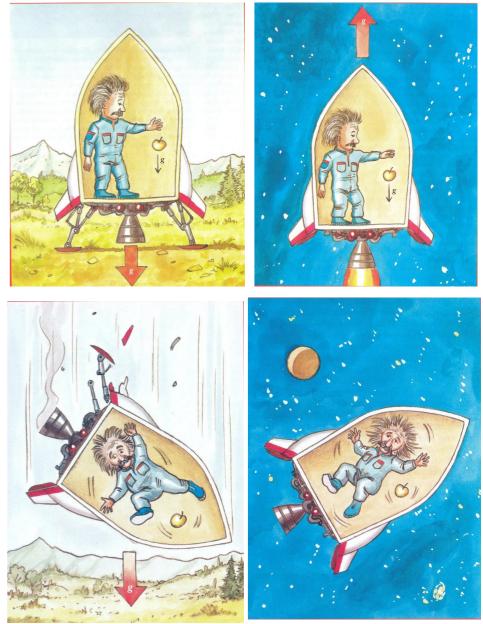


# **Basic principles of GR**

- GR is based on the following two **principles**:
- **1. Principle of equivalence** or **strong equivalence principle (EP)**: at every space-time point in an arbitrary gravitational field it is possible to choose a locally inertial reference frame such that, within a sufficiently small region of the point in question, the laws of nature take the same form as in inertial reference frame in the absence of gravitation (i.e. as in SR)
  - Weak equivalence principle (WEP) is another formulation which states the same, but refers to the laws of motion of freely falling bodies, instead of all physical laws
- **2. Principle of general covariance (PGC)** or **general principle of relativity:** a physical equation holds in a general gravitational field, if two conditions are met:
  - i. The equation holds in the absence of gravitation, i.e. it agrees with the laws of SR when the metric tensor  $g_{\mu\nu}$  equals the Minkowski tensor  $\eta_{\mu\nu}$
  - ii. The equation is generally covariant, i.e. it preserves its form under a general coordinate transformation  $x \rightarrow x'$
- According to the 2<sup>nd</sup> condition of PGC, the equation will be true in all coordinate systems if it is true in any one coordinate system
- According to the 1<sup>st</sup> condition of PGC, the equation holds in the locally inertial systems in which the effects of gravitation are absent, and hence in all other coordinate systems

## **Equivalence Principle (EP)**

- EP in Newtonian gravity rests on the equality of gravitational and inertial mass:  $m_g = m_i$
- EP in GR represents its physical basis and rests on these Einstein's observations:
  - Gravitational force as experienced locally while standing on a massive body (such as the Earth) is the same as the pseudo-force experienced by an observer in a non-inertial (accelerated) frame of reference
  - An observer in free fall in a gravitational field feels the same laws of physics as an observer which is not in a gravitational field (e.g. like astronauts in space)
- Locally, acceleration is equivalent to a gravitational field, and its effects are indistinguishable from the effects of gravity
- Bodies far away from any gravitational field move along the straight lines, and those in a gravitational field move along the shortest spacetime lines (geodesics), due to the curvature of spacetime caused by the presence of gravitational masses



## **Principle of General Covariance**

- The main significance of PGC lies in its statement about the effects of gravitation, that a physical equation will be true in a gravitational field if it is true in the absence of gravitation
- Since PE assures that a coordinate system in which the effects of gravitation are absent can be constructed only on a scale that is small compared with the spacetime distances typical of the gravitational field, PGC can only be applied on such small scales
- According to PGC, any equation can be made generally covariant by writing it in any one coordinate system, and then transforming it to other arbitrary coordinate systems
- To ensure their general covariance, equations in GR are constructed using tensors
- Because PGC is applied on a small scale compared with the scale of the gravitational field, only metric tensor  $g_{\mu\nu}$  and its first derivatives are expected to enter the generally covariant equations

## **Affine connection**

- Riemannian geometry is the study of manifolds with metrics and their associated connections (additional structures which are characterized by the curvature)
- The existence of a metric implies a certain connection, whose curvature may be thought of as that of the metric
- GR is based on the connection derived from  $g_{\mu\nu}$  which is known as affine connection, Christoffel connection, Levi-Civita connection or Riemannian connection, and its coefficients are called Christoffel symbols of the second kind
- Affine connection defined in terms of the metric tensor  $g_{\mu\nu}$  is:

$$\Gamma^{\sigma}_{\lambda\mu} = \frac{1}{2} g^{\nu\sigma} \left( \frac{\partial g_{\mu\nu}}{\partial x^{\lambda}} + \frac{\partial g_{\lambda\nu}}{\partial x^{\mu}} - \frac{\partial g_{\mu\lambda}}{\partial x^{\nu}} \right) = \frac{1}{2} g^{\nu\sigma} \left( g_{\mu\nu,\lambda} + g_{\lambda\nu,\mu} - g_{\mu\lambda,\nu} \right)$$

- The connection coefficients are symmetric in the two lower indices, but are not the components of a tensor
- In GR, affine connection  $\Gamma^{\lambda}_{\mu\nu}$  represents generalization of the Newtonian gravitational force, and metric tensor  $g_{\mu\nu}$  is generalization of the Newtonian gravitational potential (derivatives of  $g_{\mu\nu}$  determine the force  $\Gamma^{\lambda}_{\mu\nu}$ )

## **Geodesic equation**

- In GR, a geodesic generalizes the notion of a "straight line" to curved spacetime
- A freely moving or falling particle (i.e. a particle free from all external, nongravitational forces) always moves along a geodesic
- Geodesic equation can be derived directly from the Equivalence Principle or via the action principle, and it is given by:  $d^2x^{\mu} u dx^{\nu} dx^{\lambda}$

$$\frac{d^2 x^{\mu}}{ds^2} + \Gamma^{\mu}_{\nu\lambda} \frac{dx^{\nu}}{ds} \frac{dx^{\lambda}}{ds} = 0,$$

where s is a scalar parameter of motion (e.g. the proper time), and  $\Gamma^{\mu}_{\nu\lambda}$  are affine connection coefficients (Christoffel symbols)

- In flat space  $\Gamma^{\mu}_{\nu\lambda} = 0$  and geodesics reduce to straight lines defined by:  $\frac{d^2 x^{\mu}}{ds^2} = 0$
- It is not necessary to know what *s* is in order to find the motion of a particle, for geodesic equation when solved gives  $x^{\mu}(s)$ , and *s* can be eliminated to give x(t)
- Explicit expression for a geodesic can be found only when  $g_{\mu\nu}$  is known
- The left-hand-side of geodesic equation is the acceleration of a particle, and thus geodesic equation is analogous to the Newton's laws of motion
- For a massless particle such as photon, the following initial conditions are imposed:

$$0 = -g_{\mu\nu}\frac{dx^{\mu}}{ds}\frac{dx^{\nu}}{ds}$$

## Newtonian limit in GR

- Newtonian limit in GR is obtained for a particle moving slowly in a weak stationary gravitational field
- For a sufficiently **slow particle**, derivatives  $d\mathbf{x}/ds$  may be neglected with respect to derivatives cdt/ds, and then the geodesic equation is:  $\frac{d^2x^{\mu}}{ds^2} + \Gamma_{00}^{\mu} \left(\frac{c dt}{ds}\right)^2 = 0$
- In a stationary field all time derivatives of  $g_{\mu\nu}$  vanish, so:  $\Gamma^{\mu}_{00} = -\frac{1}{2}g^{\mu\nu}\frac{\partial g_{00}}{\partial x^{\nu}}$
- Metric in the weak field is equal to Minkowski metric plus a small perturbation:

$$g_{\alpha\beta} = \eta_{\alpha\beta} + h_{\alpha\beta}, \quad |h_{\alpha\beta}| \ll 1,$$

so to the first order in  $h_{\alpha\beta}$ :  $\Gamma^{\alpha}_{00} = -\frac{1}{2}\eta^{\alpha\beta}\frac{\partial h_{00}}{\partial x^{\beta}} \Rightarrow$  the equations of motion are:

$$\frac{d^2 \mathbf{x}}{ds^2} = \frac{1}{2} \left( \frac{c \, dt}{ds} \right)^2 \nabla h_{00} \quad \left| \cdot \left( \frac{ds}{c \, dt} \right)^2 \right| \Rightarrow \quad \frac{d^2 \mathbf{x}}{c^2 dt^2} = \frac{1}{2} \nabla h_{00}$$

• The corresponding Newtonian result is:  $\frac{d^2 \mathbf{x}}{dt^2} = -\nabla \phi \Rightarrow h_{00} = -\frac{2\phi}{c^2}$ , where  $\phi$  is the Newton's gravitational potential:  $\phi = -\frac{GM}{r}$  $g_{\alpha\beta} = \eta_{\alpha\beta} + h_{\alpha\beta} \Rightarrow \left[g_{00} = -\left(1 + \frac{2\phi}{c^2}\right)\right]$ 

### **Exam question**

- 1. Basic principles of GR: the principle of equivalence and the principle of general covariance
- 2. Affine connection and geodesic equation

#### Literature

- Weinberg, S., 1972, Gravitation and Cosmology: Principles and Applications of the General Theory of Relativity, Wiley-VCH
- Sean M. Carroll, 1997. *Lecture Notes on General Relativity*, arXiv, gr-qc/9712019

### **Exercise 1**

Calculate all affine connection coefficients (Christoffel symbols) Γ<sup>α</sup><sub>βγ</sub> for the two-dimensional flat Euclidean space (Euclidean plane) in polar coordinates, with metric: ds<sup>2</sup> = dr<sup>2</sup> + r<sup>2</sup>dθ<sup>2</sup>. Do all affine connection coefficients of a flat space vanish in curvilinear coordinate systems?

## Exercise 2

• Calculate all nonzero affine connection coefficients (Christoffel symbols)  $\Gamma^{\alpha}_{\beta\gamma}$  for the two-sphere metric:  $ds^2 = a^2 \left( d\theta^2 + \sin^2 \theta \, d\phi^2 \right)$ 

### Exercise 3

• Consider again the metric  $ds^2 = dr^2 + r^2 d\theta^2$  and write the 2 equations that result from the geodesic equation

#### **Exercise 4**

• For the 2-dimensional metric  $ds^2 = (dx^2 - dt^2)/t^2$ , find all nonvanishing affine connection coefficients  $\Gamma^{\mu}_{\nu\lambda}$  and derive the geodesic curves

• Nonzero components of metric tensor and inverse metric tensor:

 $g_{rr} = 1, \quad g_{\theta\theta} = r^2 \quad \wedge \quad g^{rr} = 1, \quad g^{\theta\theta} = r^{-2} \quad \Rightarrow$ 

• The only nonzero derivative of metric tensor is:  $g_{\theta\theta,r} = 2r$ 

$$\begin{split} \Gamma_{\lambda\mu}^{\sigma} &= \frac{1}{2} g^{\nu\sigma} \left( g_{\mu\nu,\lambda} + g_{\lambda\nu,\mu} - g_{\mu\lambda,\nu} \right) \quad \Rightarrow \\ \Gamma_{rr}^{r} &= \frac{1}{2} g^{r\rho} (g_{r\rho,r} + g_{\rho r,r} - g_{rr,\rho}) \\ &= \frac{1}{2} g^{rr} (g_{rr,r} + g_{rr,r} - g_{rr,r}) + \frac{1}{2} g^{r\theta} (g_{r\theta,r} + g_{\theta r,r} - g_{rr,\theta}) \\ &= \frac{1}{2} \cdot 1 \cdot (0 + 0 - 0) + \frac{1}{2} \cdot 0 \cdot (0 + 0 - 0) = 0 \\ \Gamma_{\theta\theta}^{r} &= \frac{1}{2} g^{r\rho} (g_{\theta\rho,\theta} + g_{\rho\theta,\theta} - g_{\theta\theta,\rho}) = \frac{1}{2} g^{rr} (g_{\theta r,\theta} + g_{r\theta,\theta} - g_{\theta\theta,r}) \\ &= \frac{1}{2} \cdot 1 \cdot (0 + 0 - 2r) = -r \end{split}$$

• In the similar way:  $\Gamma_{\theta r}^r = \Gamma_{r\theta}^r = 0$ ,  $\Gamma_{rr}^\theta = 0$ ,  $\Gamma_{r\theta}^\theta = \Gamma_{\theta r}^\theta = \frac{1}{r}$   $\Gamma_{\theta\theta}^\theta = 0$ 

• As it can be seen from this example, not all affine connection coefficients of a flat space vanish in curvilinear coordinate systems

Nonzero components of metric tensor and inverse metric tensor: g<sub>θθ</sub> = a<sup>2</sup>, g<sub>φφ</sub> = a<sup>2</sup> sin<sup>2</sup> θ ∧ g<sup>θθ</sup> = a<sup>-2</sup>, g<sup>φφ</sup> = a<sup>-2</sup> sin<sup>-2</sup> θ
Nonzero Christoffel symbols: Γ<sup>θ</sup><sub>φφ</sub> = − sin θ cos θ, Γ<sup>φ</sup><sub>θφ</sub> = Γ<sup>φ</sup><sub>φθ</sub> = cot θ

According to the solution of the Exercise 1, the nonzero affine connection coefficients for this metric are:  $\Gamma_{\theta\theta}^r = -r$  and  $\Gamma_{r\theta}^{\theta} = \Gamma_{\theta r}^{\theta} = \frac{1}{r}$ Therefore, the geodesic equation is:  $\frac{d^2 x^{\mu}}{ds^2} + \Gamma_{\nu\lambda}^{\mu} \frac{dx^{\nu}}{ds} \frac{dx^{\lambda}}{ds} = 0 \Rightarrow$  $\frac{d^2 r}{ds^2} + \Gamma_{\theta\theta}^r \frac{d\theta}{ds} \frac{d\theta}{ds} = 0 \land \frac{d^2 \theta}{ds^2} + 2\Gamma_{r\theta}^{\theta} \frac{dr}{ds} \frac{d\theta}{ds} = 0 \Rightarrow$  $\frac{d^2 r}{ds^2} = r \left(\frac{d\theta}{ds}\right)^2 \land \frac{d^2 \theta}{ds^2} + \frac{2}{r} \frac{dr}{ds} \frac{d\theta}{ds} = 0$ 

- Nonzero components of metric tensor and inverse metric tensor:
  - $g_{tt} = -t^{-2}, \quad g_{xx} = t^{-2} \quad \land \quad g^{tt} = -t^2, \quad g^{xx} = t^2 \quad \Rightarrow$
- Nonzero derivatives of metric tensor:  $g_{tt,t} = 2t^{-3}$ ,  $g_{xx,t} = -2t^{-3}$
- Nonzero Christoffel symbols:  $\Gamma_{tt}^t = \Gamma_{xx}^t = \Gamma_{tx}^x = \Gamma_{xt}^x = -\frac{1}{t}$
- Geodesics:  $\frac{d^2 x^{\mu}}{ds^2} + \Gamma^{\mu}_{\nu\lambda} \frac{dx^{\nu}}{ds} \frac{dx^{\lambda}}{ds} = 0 \quad \stackrel{x^{\mu}=t}{\Longrightarrow} \quad \frac{d^2 t}{ds^2} = \Gamma^t_{tt} \left(\frac{dt}{ds}\right)^2 + \Gamma^t_{xx} \left(\frac{dx}{ds}\right)^2 = 0$  $\frac{d^2 x^{\mu}}{ds^2} + \Gamma^{\mu}_{\nu\lambda} \frac{dx^{\nu}}{ds} \frac{dx^{\lambda}}{ds} = 0 \quad \stackrel{x^{\mu} = x}{\Longrightarrow} \quad \frac{d^2 x}{ds^2} = 2\Gamma^x_{tx} \frac{dt}{ds} \frac{dx}{ds} = 0$  $(2) \Rightarrow \frac{d}{ds} \left(\frac{dx}{ds}\right) = \frac{d}{ds} \left(\ln t^2\right) \frac{dx}{ds} \iff \frac{\frac{d}{ds} \left(\frac{dx}{ds}\right)}{dx} = \frac{d}{ds} \left(\ln t^2\right) \Leftrightarrow \checkmark$ ds  $\frac{d}{ds}\left(\ln\frac{dx}{ds}\right) = \frac{d}{ds}\left(\ln t^2\right) \Rightarrow \frac{dx}{ds} = ct^2 \quad (3) \stackrel{\text{metric}}{\Longrightarrow} \left(\frac{dt}{ds}\right)^2 = c^2t^4 - t^2 \Rightarrow$  $\frac{dt}{ds} = \pm t\sqrt{c^2t^2 - 1} \xrightarrow{(3)} \frac{dx}{dt} = \pm \frac{ct}{\sqrt{c^2t^2 - 1}} \Rightarrow x - x_0 = \pm \sqrt{t^2 - c^{-2}} \Rightarrow$ • Geodesics are hyperbolas asymptotic to the light cones:  $\frac{t^2}{(1/c)^2} - \frac{(x-x_0)^2}{(1/c)^2} = 1$